

DSP-1760 光纤陀螺仪

单轴或多轴高性能光纤陀螺仪

KVH



Key Features

- 优异的偏置不稳定性
 $\leq 0.05^\circ/\text{hr}$, 1σ (典型值) ;
 $\leq 0.1^\circ/\text{小时}$, 1σ (最大)
- 单轴或多轴高性能FOG
- 所有封装的变体都可用Micro-D连接器或圆形连接器
- Micro-D连接器提供无外壳的变体
- 角度随机游走 (ARW) $\leq 0.012^\circ/\sqrt{\text{hr}}$ ($0.7^\circ/\text{hr} / \sqrt{\text{Hz}}$)
- 带宽 (容纳) : $\geq 440\text{Hz}$ 带宽 (容纳) : $\geq 1000\text{Hz}$
- 提供九种配置:
- 容纳1轴, 2轴或3轴
- 带Micro-D连接器的无外壳1轴, 2轴或3轴拴在PCB上
- KVH E•Core®ThinFiber术

紧凑的单轴或多轴光纤陀螺仪，旨在最大程度地简化集成
KVH的DSP-1760光纤陀螺仪 (FOG) 结合了单轴或多轴

易于集成的外壳中有世界上最小的高性能FOG，也没有提供OEM配置的外壳。DSP-1760 FOG在偏置稳定性，比例因子和角度随机游动方面具有出色的性能，并提供9种配置以解决最具挑战性的设计项目。

DSP-1760 FOG非常适合空中，陆地或海上稳定和指示应用。由于它的多功能性以及准确，可靠的输出，它也可以用于导航，制导和控制系统。

专为灵活性和性能而设计

DSP-1760 FOG提供单轴或多轴陀螺仪配置，

高带宽，极低噪声的传感器。DSP-1760 FOG使用KVH专有的E•Core ThinFiber (世界上最小的D形光纤)，为客户提供两种接口选择：Micro-D或圆形连接器。此外，DSP-1760 FOG在内部集成了磁屏蔽。陀螺仪外壳，在磁环境有问题的系统中提供改进的性能。

卓越的质量和可靠性

KVH是唯一一家拉制自己的光纤的美国FOG制造商，

确保质量一致，性能保证，稳定可靠

在每个陀螺仪和陀螺仪系统中开启到开启偏置的重复性。

DSP-1760 FOG是固态的，具有改进的电子设计，在诸如偏置稳定性，ARW和比例因子非线性之类的关键性能领域提供了显着改进。

独家技术

KVH专有的偏振保持E•Core ThinFiber可在小得多的陀螺仪（例如DSP-1760）中提供出色的精度性能。通过减小KVH的标准E•Core光纤的总直径最终的E•Core ThinFiber光电路的厚度仅为170微米，大大提高了我们标准尺寸陀螺仪的精度，并产生了可提供极高带宽和低噪声的小型陀螺仪。



Ideal for the stabilization and orientation of high-speed gimbals, the versatile and lightweight DSP-1760 FOG offers nine configurations for ultimate integration flexibility.



Pipelines deliver massive amounts of crude daily and ensuring safe operation is key. The KVH DSP-1760, coupled to additional sensors, provides these inspection robots with extremely accurate angular data.

KVH DSP-1760 Fiber Optic Gyro

Performance Specifications

Input Rate (max)	$\pm 490^\circ/\text{sec}$
Bias Instability (25°C)	$\leq 0.1^\circ/\text{hr}, 1\sigma \text{ (max)}, \leq 0.05^\circ/\text{hr}, 1\sigma \text{ (typical)}$
Bias vs. Temperature ($\leq 1^\circ\text{C}/\text{min}$)	$\leq 1.5^\circ/\text{hr}, 1\sigma \text{ (max)}, \leq 1^\circ/\text{hr}, 1\sigma \text{ (typical)}$
Bias Offset (25°C)	$\pm 2^\circ/\text{hr}$
Scale Factor Non-linearity (full rate, 25°C)	$\leq 50 \text{ ppm}, 1\sigma$
Scale Factor vs. Temperature ($\leq 1^\circ\text{C}/\text{min}$)	$\leq 200 \text{ ppm}, 1\sigma \text{ (max)}, \leq 100 \text{ ppm}, 1\sigma \text{ (typical)}$
Angle Random Walk (25°C)	$\leq 0.012^\circ/\sqrt{\text{hr}} \text{ (} 0.7^\circ/\text{hr}/\sqrt{\text{Hz}} \text{)}$
Bandwidth (-3 dB)	Housed: $\geq 440 \text{ Hz}$ Unhoused: $\geq 1000 \text{ Hz}$

Electrical/Mechanical Interface

Initialization Time	$\leq 1.25 \text{ secs housed}, \leq 1.5 \text{ secs unhoused}$
Data Interface	Asynchronous or Synchronous RS-422
Baud Rate	User Selectable 9.6 Kbps to 921.6 Kbps (housed) User Selectable 9.6 kbps to 4147 Kbps (unhoused)
Data Rate	User Selectable 1 to 1000 Hz (housed) User Selectable 1 to 5000 Hz (unhoused)

Physical Specifications

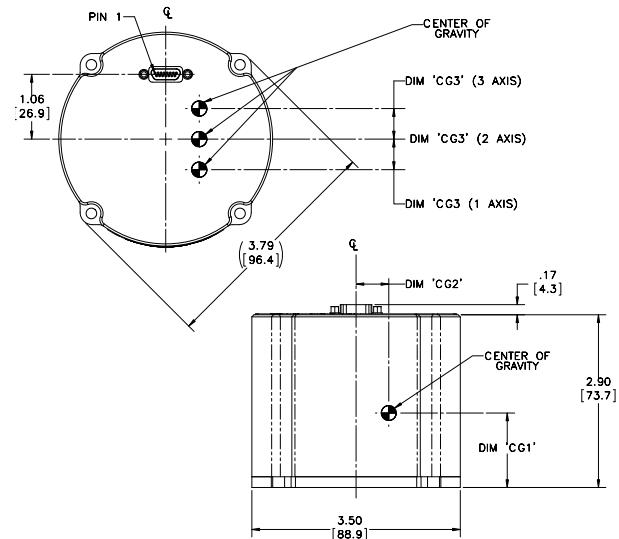
Dimensions - Housed (max)	88.9 mm Dia x 73.7 mm H (3.5" x 2.9")
Dimensions - Unhoused	PCB stack: 81 mm Dia x 24.8 mm H (3.19" x 0.978") (nominal) Gyro sensor: 44.7 mm Dia x 21.8 mm H (1.76" x 0.86")
Weight - Housed (max)	Single-axis: 0.50 kg (1.1 lbs.) Dual-axis: 0.54 kg (1.2 lbs.) 3-axis: 0.60 kg (1.3 lbs.)
Weight - Unhoused (nominal)	PCB stack: 0.11 kg (0.25 lbs.) Gyro sensor: 0.07 kg (0.16 lbs.) Flex cables: 0.0005 kg (0.001 lbs.)
Power Consumption	Single-axis: 6 W (max), 3W (typical) Dual-axis: 7 W (max), 4W (typical) 3-axis: 8 W (max), 5W (typical)
Input Voltage	+9 to +36 VDC

Environmental Specifications

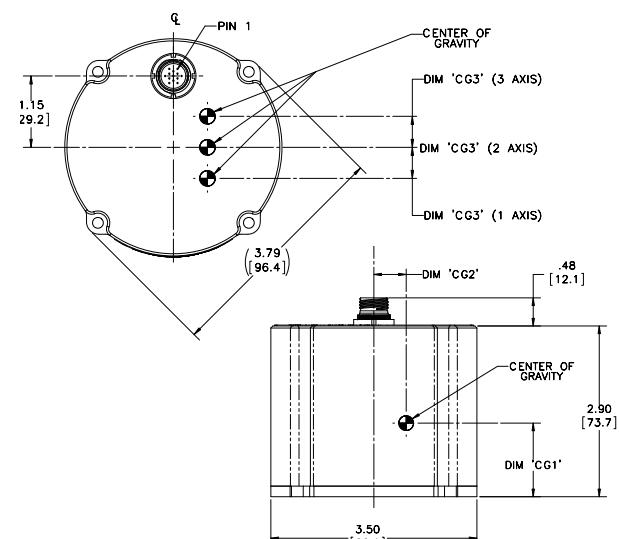
Temperature (operating)	-40°C to +75°C (-40°F to +167°F)
Shock (operating)	25 g, 11 msec, sawtooth
Vibration (operating)	8 g rms, 20-2000 Hz, random

Housed DSP-1760s

Micro-D Connector Option

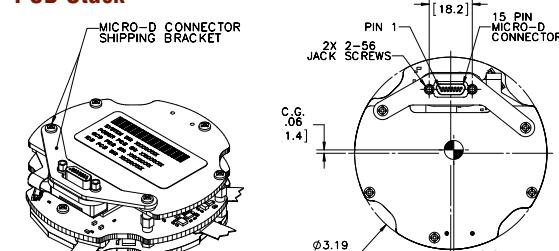


Circular Connector Option

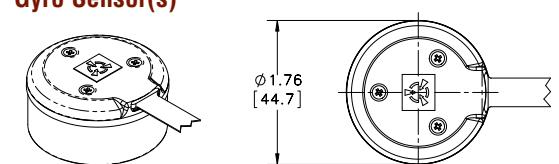


Unhoused DSP-1760s

PCB Stack



Gyro Sensor(s)*



*1, 2, or 3 gyro sensors

